# Flow: Waves and instabilities in stationary plasmas



- Introduction: theoretical themes for a complete MHD description of laboratory and astrophysical plasmas, static versus stationary plasmas;
- **Spectral theory of stationary plasmas:** Frieman–Rotenberg formalism for waves and instabilities, quadratic eigenvalue problem gives complex eigenvalues, implications of the Doppler shift for the continuous spectra;
- Kelvin–Helmholtz instability of streaming plasmas: gravitating plasma with an interface where the velocity changes discontinuously, influence of the magnetic field;
- Magneto-rotational instability of rotating plasmas: derivation of the dispersion equation, growth rates of instabilities, application to accretion disks.

#### Theoretical themes

- In overview of magnetic structures and dynamics (Chap. 8), we encountered:
  - Central importance of magnetic flux tubes  $\Rightarrow$  Cylindrical plasmas, 1D: f(r)[Volume 1: Chap. 9]
  - Astrophysical flows (winds, disks, jets) ⇒ Plasmas with background flow
     [this lecture, Volume 2: MHDF.pdf]
  - Explosive phenomena due to reconnection  $\Rightarrow$  **Resistive MHD**

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[Volume 2: MHDR.pdf]
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- Magnetic confinement for fusion (tokamak)  $\Rightarrow$  Toroidal plasmas, 2D:  $f(r, \vartheta)$  [Volume 2: MHDT.pdf]
- Shocks, transonic flows, dynamos, turbulence ⇒ Nonlinear MHD
   [Volume 2: MHDS.pdf]
- All plasma dynamics (e.g. space weather)  $\Rightarrow$  **Computational MHD**

[Volume 2: ... ]

• MHD with background flow is the most urgent topic (also for fusion research since divertors and neutral beam injection cause significant flows in tokamaks).

 $\Rightarrow$  From static (v = 0) to stationary (v  $\neq$  0) plasmas!

#### Static versus stationary plasmas

• Starting point is the set of nonlinear ideal MHD equations:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0, \qquad (1)$$

$$\rho(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v}) + \nabla p - \mathbf{j} \times \mathbf{B} - \rho \mathbf{g} = 0, \qquad \mathbf{j} = \nabla \times \mathbf{B}, \qquad (2)$$

$$\frac{\partial p}{\partial t} + \mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} = 0, \qquad (3)$$

$$\frac{\partial \mathbf{B}}{\partial t} - \nabla \times (\mathbf{v} \times \mathbf{B}) = 0, \qquad \nabla \cdot \mathbf{B} = 0, \tag{4}$$

with gravitational acceleration  $\mathbf{g} = -\nabla \Phi_{gr}$  due to external gravity field  $\Phi_{gr}$ .

• Recall the simplicity of static equilibria ( $\partial/\partial t = 0$ ,  $\mathbf{v} = 0$ ),

$$\nabla p = \mathbf{j} \times \mathbf{B} + \rho \mathbf{g}, \qquad \mathbf{j} = \nabla \times \mathbf{B}, \qquad \nabla \cdot \mathbf{B} = 0,$$
 (5)

with perturbations described by self-adjoint operator  $\mathbf{F}$  with real eigenvalues  $\omega^2$ :

$$\mathbf{F}(\boldsymbol{\xi}) = \rho \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2} \quad \Rightarrow \quad \mathbf{F}(\hat{\boldsymbol{\xi}}) = -\rho \omega^2 \hat{\boldsymbol{\xi}} \,. \tag{6}$$

• Can one construct a similar powerful scheme for stationary plasmas ( $\mathbf{v} \neq 0$ )?

#### Stationary equilibria

• Basic nonlinear ideal MHD equations for stationary equilibria ( $\partial/\partial t = 0$ ):

$$\nabla \cdot (\rho \mathbf{v}) = 0, \tag{7}$$

$$\rho \mathbf{v} \cdot \nabla \mathbf{v} + \nabla p = \mathbf{j} \times \mathbf{B} + \rho \mathbf{g}, \qquad \mathbf{j} = \nabla \times \mathbf{B},$$
(8)

$$\mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} = 0, \qquad (9)$$

$$\nabla \times (\mathbf{v} \times \mathbf{B}) = 0, \qquad \nabla \cdot \mathbf{B} = 0.$$
 (10)

 $\Rightarrow$  None of them trivially satisfied now (except for simple geometries)!

• For *plane gravitating plasma slab,* equilibrium unchanged w.r.t. static case:

$$(p + \frac{1}{2}B^2)' = -\rho g \qquad (' \equiv d/dx).$$
 (11)

• For cylindrical plasma, the equilibrium is changed significantly by the centrifugal acceleration,  $-\mathbf{v} \cdot \nabla \mathbf{v} = (v_{\theta}^2/r)\mathbf{e}_r$ :

$$(p + \frac{1}{2}B^2)' + \frac{1}{r}B_{\theta}^2 = \frac{1}{r}\rho v_{\theta}^2 - \rho \Phi_{\rm gr}' \qquad (' \equiv d/dr).$$
(12)

⇒ Modifications for plane and cylindrical stationary flows quite different: translations and rotations are physically different phenomena. Frieman–Rotenberg formalism

[Rev. Mod. Phys. 32, 898 (1960)]

Spectral theory for general stationary equilibria (no further simplifying assumptions):

• First, construct displacement vector  $\boldsymbol{\xi}$ connecting perturbed flow at position  $\mathbf{r}$ with unperturbed flow at position  $\mathbf{r}^0$ :

$$\mathbf{r}(\mathbf{r}^0, t) = \mathbf{r}^0 + \boldsymbol{\xi}(\mathbf{r}^0, t)$$
. (13)

• In terms of the coordinates  $(\mathbf{r}^0, t)$ , the equilibrium is time-independent:  $\rho = \rho^0(\mathbf{r}^0)$ , etc., satisfiying (7)–(10).

• Gradient 
$$\nabla = (\nabla \mathbf{r}^0) \cdot \nabla^0 = \nabla (\mathbf{r} - \boldsymbol{\xi}) \cdot \nabla^0 \approx \nabla^0 - (\nabla^0 \boldsymbol{\xi}) \cdot \nabla^0$$
, (14)

and Lagrangian time derivative 
$$\frac{D}{Dt} \equiv \frac{\partial}{\partial t} \Big|_{\mathbf{r}^0} + \mathbf{v}^0 \cdot \nabla^0, \qquad (1)$$

yield expression for the velocity at the perturbed trajectory:

$$\mathbf{v}(\mathbf{r}^{0} + \boldsymbol{\xi}, t) \equiv \frac{\mathrm{D}\mathbf{r}}{\mathrm{D}t} = \frac{\mathrm{D}\mathbf{r}^{0}}{\mathrm{D}t} + \frac{\mathrm{D}\boldsymbol{\xi}}{\mathrm{D}t} = \mathbf{v}^{0} + \mathbf{v}^{0} \cdot \nabla^{0}\boldsymbol{\xi} + \frac{\partial\boldsymbol{\xi}}{\partial t}.$$
 (16)



5)

Frieman–Rotenberg formalism (cont'd)

• Linearization of Eqs. (1), (3), (4) gives perturbed quantities in terms of  $\xi$  alone:

$$\rho \approx \rho^0 - \rho^0 \nabla^0 \cdot \boldsymbol{\xi} \qquad \qquad = \rho^0 + \rho_{\rm E}^1 + \boldsymbol{\xi} \cdot \nabla^0 \rho^0 \,, \tag{17}$$

$$p \approx p^{0} - \gamma p^{0} \nabla^{0} \cdot \boldsymbol{\xi} \qquad \qquad = p^{0} + \pi + \boldsymbol{\xi} \cdot \nabla^{0} p^{0} , \qquad (\pi \equiv p_{\rm E}^{1})$$
(18)

$$\mathbf{B} \approx \mathbf{B}^{0} + \mathbf{B}^{0} \cdot \nabla^{0} \boldsymbol{\xi} - \mathbf{B}^{0} \nabla^{0} \cdot \boldsymbol{\xi} = \mathbf{B}^{0} + \mathbf{Q} + \boldsymbol{\xi} \cdot \nabla^{0} \mathbf{B}^{0}, \quad (\mathbf{Q} \equiv \mathbf{B}_{\mathrm{E}}^{1}) (19)$$

where we will now drop the superscripts  $^{0}$  (since everything has this superscript).

• Substitution in Eq. (2) (+ algebra!)  $\Rightarrow$  spectral equation for equilibria with flow:

$$\rho \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2} + 2\rho \mathbf{v} \cdot \nabla \frac{\partial \boldsymbol{\xi}}{\partial t} - \mathbf{G}(\boldsymbol{\xi}) = 0, \qquad (20)$$

$$\mathbf{G} \equiv \mathbf{F} + \nabla \cdot \left( \boldsymbol{\xi} \,\rho \mathbf{v} \cdot \nabla \mathbf{v} - \rho \mathbf{v} \mathbf{v} \cdot \nabla \boldsymbol{\xi} \right),\tag{21}$$

$$\mathbf{F} \equiv -\nabla \pi - \mathbf{B} \times (\nabla \times \mathbf{Q}) + (\nabla \times \mathbf{B}) \times \mathbf{Q} + (\nabla \Phi) \nabla \cdot (\rho \boldsymbol{\xi}).$$

• For normal modes,  $\boldsymbol{\xi} \sim \exp(-i\omega t)$ , a quadratic eigenvalue problem is obtained:

$$\mathbf{G}(\boldsymbol{\xi}) + 2\mathrm{i}\rho\omega\mathbf{v}\cdot\nabla\boldsymbol{\xi} + \rho\omega^{2}\boldsymbol{\xi} = 0, \qquad (22)$$

where the generalised force operator G is selfadjoint (like F in the static case) but eigenvalues  $\omega$  are complex because of the Doppler shift operator  $iv \cdot \nabla$ .

### Spectral equation for plane slab

• For the plane slab model of Chapter 7, extended with a plane shear flow field,

$$\mathbf{B} = B_y(x)\mathbf{e}_y + B_z(x)\mathbf{e}_z, \quad \rho = \rho(x), \quad p = p(x),$$
  
$$\mathbf{v} = v_y(x)\mathbf{e}_y + v_z(x)\mathbf{e}_z, \quad (23)$$

the equilibrium is unchanged and the two new terms in G yield:  $\mathbf{v} \cdot \nabla \mathbf{v} = 0$  and  $-\nabla \cdot (\rho \mathbf{v} \mathbf{v} \cdot \nabla \boldsymbol{\xi}) = -\rho (\mathbf{v} \cdot \nabla)^2 \boldsymbol{\xi}$ , so that the eigenvalue problem (22) becomes:

$$\mathbf{G}(\boldsymbol{\xi}) + 2\mathrm{i}\rho\omega\mathbf{v}\cdot\nabla\boldsymbol{\xi} + \rho\omega^{2}\boldsymbol{\xi} = \mathbf{F}(\boldsymbol{\xi}) + \rho(\omega + \mathrm{i}\mathbf{v}\cdot\nabla)^{2} = 0$$

$$\Rightarrow \mathbf{F}(\boldsymbol{\xi}) = -\rho \widetilde{\omega}^2 \, \boldsymbol{\xi} \,, \qquad \widetilde{\omega} \equiv \omega + \mathrm{i} \mathbf{v} \cdot \nabla \,. \tag{24}$$

• Hence, the equations for the static slab remain valid with the replacement

$$\omega \rightarrow \widetilde{\omega}(x) \equiv \omega - \Omega_0(x), \quad \Omega_0 \equiv \mathbf{k}_0 \cdot \mathbf{v}(x),$$
 (25)

where  $\Omega_0(x)$  is the local Doppler shift and  $\tilde{\omega}(x)$  is the *local Doppler shifted frequency* observed in a local frame co-moving with the plasma at the vertical position x.

• Since  $\widetilde{\omega}$  depends on x, eigenvalues will be shifted by some average of  $\Omega_0(x)$  across the layer. If a static equilibrium is unstable (eigenvalue on positive imaginary axis), for the corresponding equilibrium with flow that eigenvalue moves into the complex plane and becomes an *overstable mode*.

### HD continua for plane shear flow

• How are the MHD waves affected by background flow of the plasma?

First, consider **continuous spectrum in the HD case** for plane slab geometry, inhomogeneous fluid with horizontal flow:

$$\mathbf{v} = v_y(x)\mathbf{e}_y + v_z(x)\mathbf{e}_z \,.$$

• Lagrangian time derivative:

$$(\mathrm{D}f/\mathrm{d}t)_1 \equiv (\partial f/\partial t + \mathbf{v} \cdot \nabla f)_1 = -\mathrm{i}\,\widetilde{\omega}f_1 + f_0' v_{1x}\,, \qquad \widetilde{\omega} \equiv \omega - \mathbf{k_0} \cdot \mathbf{v}\,,$$

 $\widetilde{\omega}(x)$ : frequency observed in local frame co-moving with fluid layer at position x.

• Singularities when  $\tilde{\omega} = 0$  somewhere in the fluid  $\Rightarrow$  HD flow continuum { $\Omega_0(x)$ }, consisting of the zeros of the local Doppler shifted frequency

$$\widetilde{\omega} \equiv \omega - \Omega_0(x), \quad \Omega_0 \equiv -i \mathbf{v} \cdot \nabla = \mathbf{k_0} \cdot \mathbf{v}, \quad \text{on the interval } x_1 \leq x \leq x_2.$$

These have been extensively investigated in the hydrodynamics literature. [Lin 1955; Case 1960; Drazin and Reid, Hydrodynamic Stability (Cambridge, 2004)]

#### MHD continua for plane shear flow

• Forward (+) / backward (-) Alfvén and slow continua, and fast cluster points:

$$\Omega_A^{\pm} \equiv \Omega_0 \pm \omega_A, \qquad \omega_A \equiv F/\sqrt{\rho}, \qquad F \equiv -i \mathbf{B} \cdot \nabla = \mathbf{k}_0 \cdot \mathbf{B},$$
  
$$\Omega_S^{\pm} \equiv \Omega_0 \pm \omega_S, \qquad \omega_S \equiv \sqrt{\frac{\gamma p}{\gamma p + B^2}} F/\sqrt{\rho}, \quad \Omega_0 \equiv -i \mathbf{v} \cdot \nabla = \mathbf{k}_0 \cdot \mathbf{v},$$
  
$$\Omega_F^{\pm} \equiv \pm \infty.$$

• The flow contribution to the MHD continua creates the following ordering of the local frequencies (which are all real) in the co-moving frame:

 $\Omega_F^- \le \Omega_{f0}^- \le \Omega_A^- \le \Omega_{s0}^- \le \Omega_S^- \le \Omega_0 \le \Omega_S^+ \le \Omega_{s0}^+ \le \Omega_A^+ \le \Omega_{f0}^+ \le \Omega_F^+.$ 

- The discrete spectra are monotonic for real  $\omega$  outside these frequencies.
- In the limit  $\mathbf{B} \to 0$ , the Alfvén and slow continua collapse into the flow continuum,

$$\Omega_A^{\pm} \to \Omega_0$$
,  $\Omega_S^{\pm} \to \Omega_0$  (whereas  $\Omega_F^{\pm}$  remains at  $\pm \infty$ ).

Vice versa, the HD flow continuum is absorbed by the MHD continua when  $B \neq 0$ . Hence, contrary to the literature, there is no separate flow continuum in MHD! [Goedbloed, Beliën, van der Holst, Keppens, Phys. Plasmas 11, 4332 (2004)]

### Real parts of HD & MHD spectra

• **HD spectrum** of fluid flow:



• MHD spectrum of plasma flow:



#### Kelvin–Helmholtz instability: equilibrium

- Extend Rayleigh–Taylor instability of plasma–vacuum interface (sheets 6-36 6-42) to plasma–plasma interface with two different velocities (see figure on 6-36): Rayleigh–Taylor + Kelvin–Helmholtz!
- Upper layer ( $0 < x \le a$ ):

$$\rho = \text{const}, \quad \mathbf{v} = (0, v_y, v_z) = \text{const}, \quad \mathbf{B} = (0, B_y, B_z) = \text{const},$$
$$p' = -\rho g \qquad \Rightarrow \quad p = p_0 - \rho g x \quad (p_0 \ge \rho g a). \tag{26}$$

Lower layer (  $-b \le x < 0$ ):

$$\hat{\rho} = \text{const}, \quad \hat{\mathbf{v}} = (0, \hat{v}_y, \hat{v}_z) = \text{const}, \quad \hat{\mathbf{B}} = (0, \hat{B}_y, \hat{B}_z) = \text{const},$$
$$\hat{p}' = -\hat{\rho}g \qquad \Rightarrow \quad \hat{p} = \hat{p}_0 - \hat{\rho}gx. \quad (27)$$

• Jumps at the interface (x = 0):

BC: 
$$p_0 + \frac{1}{2}B_0^2 = \hat{p}_0 + \frac{1}{2}\hat{B}_0^2$$
 (pressure balance), (28)  
 $\Rightarrow \mathbf{j}^* = \mathbf{n} \times [\mathbf{B}] = \mathbf{e}_x \times (\mathbf{B} - \hat{\mathbf{B}})$  (surface current),  
 $\Rightarrow \boldsymbol{\omega}^* = \mathbf{n} \times [\mathbf{v}] = \mathbf{e}_x \times (\mathbf{v} - \hat{\mathbf{v}})$  (surface vorticity).

#### Kelvin–Helmholtz instability: normal modes

• Now (in contrast to energy principle analysis of 6-36 – 6-42), normal mode analysis:

$$\boldsymbol{\xi} \sim \exp\left[\mathrm{i}(k_y y + k_z z - \omega t)\right].$$

• For *incompressible plasma*, taking limit  $c^2 \equiv \gamma p / \rho \to \infty$  of Eq. (50) on sheet 7-20, with plane flow, replacing  $\omega \to \tilde{\omega}$  (Eq. (25) of sheet F-7), basic ODE becomes:

$$\frac{d}{dx}\left[\rho(\widetilde{\omega}^2 - \omega_A^2)\frac{d\xi}{dx}\right] - k_0^2\left[\rho(\widetilde{\omega}^2 - \omega_A^2) + \rho'g\right]\,\xi = 0\,.$$
(30)

Doppler shifted freq.  $\widetilde{\omega} \equiv \omega - \Omega_0$ ,  $\Omega_0 \equiv \mathbf{k}_0 \cdot \mathbf{v}$ ; Alfvén freq.  $\omega_A \equiv \mathbf{k}_0 \cdot \mathbf{B} / \sqrt{\rho_0}$ .

• In this case, all equilibrium quantities constant so that ODEs simplify to equations with constant coefficients:

$$\xi'' - k_0^2 \xi = 0$$
, BC  $\xi(a) = 0 \implies \xi = C \sinh[k_0(a - x)]$ , (31)

$$\hat{\xi}'' - k_0^2 \hat{\xi} = 0$$
, BC  $\hat{\xi}(-b) = 0 \implies \hat{\xi} = \hat{C} \sinh[k_0(x+b)]$ . (32)

 $\Rightarrow$  Surface modes (cusp-shaped eigenfunctions). This part is trivial, contains hardly any physics. Physics comes from the BCs at x = 0 determining the eigenvalues.

#### Kelvin–Helmholtz instability: interface conditions

- Now (in contrast to energy principle analysis of 6-36–6-42), need both interface conditions (model II\* BCs), to determine relative amplitude  $\hat{C}/C$  and eigenvalue  $\omega$ :
  - First interface condition (continuity of normal velocity):

$$\llbracket \mathbf{n} \cdot \boldsymbol{\xi} \rrbracket = 0 \quad \Rightarrow \quad \boldsymbol{\xi}(0) = \hat{\boldsymbol{\xi}}(0) = 0 \quad \Rightarrow \quad C \sinh \, k_0 a = \hat{C} \sinh \, k_0 b \,. \tag{33}$$

- Second interface condition (pressure balance):

$$\left[\!\left[\Pi + \mathbf{n} \cdot \boldsymbol{\xi} \,\mathbf{n} \cdot \nabla (p + \frac{1}{2}B^2)\right]\!\right] = 0, \quad \Pi \equiv -\gamma p \nabla \cdot \boldsymbol{\xi} - \boldsymbol{\xi} \cdot \nabla p + \mathbf{B} \cdot \mathbf{Q}, \quad (34)$$

where  $\gamma p \nabla \cdot \boldsymbol{\xi}$  is undetermined. Determine  $\Pi$  from expression for compressible plasmas, Book, Eq. (7.99), with  $\omega$  replaced by  $\widetilde{\omega}$  and taking limit  $\gamma \to \infty$ :

$$\Pi \equiv -\frac{N}{D}\xi' + \rho g \,\frac{\widetilde{\omega}^2(\widetilde{\omega}^2 - \omega_A^2)}{D}\xi \ \to \ \frac{\rho}{k_0^2}(\widetilde{\omega}^2 - \omega_A^2)\xi' \,. \tag{35}$$

• Dividing the second by the first interface condition then gives

$$\left[ \frac{\rho}{k_0^2} (\widetilde{\omega}^2 - \omega_A^2) \frac{\xi'}{\xi} - \rho g \right] = 0 \quad \Rightarrow \quad \text{eigenvalue } \omega \,. \tag{36}$$

#### Kelvin–Helmholtz instability: dispersion equation

• Inserting solutions (31) and (32) for  $\xi$  and  $\hat{\xi}$  yields the **dispersion equation**:

$$-\rho\left[(\omega-\Omega_0)^2-\omega_A^2\right]\coth(k_0a)-k_0\rho g=\hat{\rho}\left[(\omega-\hat{\Omega}_0)^2-\hat{\omega}_A^2\right]\coth(k_0b)-k_0\hat{\rho}g.$$
(37)

Describes magnetic field line bending (Alfvén), gravity (RT), velocity difference (KH).

- Approximations for long wavelengths ( $k_0 x \ll 1$ ):  $\operatorname{coth} k_0 x \approx (k_0 x)^{-1}$ , short wavelengths ( $k_0 x \gg 1$ ):  $\operatorname{coth} k_0 x \approx 1$ .
- Solutions for short wavelengths (walls effectively at  $\infty$  and  $-\infty$ ):

$$\omega = \frac{\rho \Omega_0 + \hat{\rho} \hat{\Omega}_0}{\rho + \hat{\rho}} \pm \sqrt{-\frac{\rho \hat{\rho} (\Omega_0 - \hat{\Omega}_0)^2}{(\rho + \hat{\rho})^2} + \frac{\rho \omega_A^2 + \hat{\rho} \hat{\omega}_A^2}{\rho + \hat{\rho}} - \frac{k_0 (\rho - \hat{\rho})g}{\rho + \hat{\rho}}} \,. \tag{38}$$

 $\Rightarrow$  Stable (square root real) if

$$(\mathbf{k}_0 \cdot \mathbf{B})^2 + (\mathbf{k}_0 \cdot \hat{\mathbf{B}})^2 > \frac{\rho \hat{\rho}}{\rho + \hat{\rho}} \left[ \mathbf{k}_0 \cdot (\mathbf{v} - \hat{\mathbf{v}}) \right]^2 + k_0 (\rho - \hat{\rho}) g \,.$$
(39)  
magnetic shear K–H drive R–T drive

Kelvin–Helmholtz instability: generic transitions

• Pure KH instability ( $\mathbf{B} = \hat{\mathbf{B}} = 0, g = 0, \mathbf{k}_0 \parallel \mathbf{v} \parallel \hat{\mathbf{v}}$ ):  $\omega = k_0 \left[ \frac{\rho v + \hat{\rho} \hat{v}}{\rho + \hat{\rho}} \pm i \frac{\sqrt{\rho \hat{\rho}}}{\rho + \hat{\rho}} |v - \hat{v}| \right].$ (40)

 $\Rightarrow$  Degeneracy of Doppler mode  $\omega = k_0 v$  lifted by  $v \neq \hat{v}$ .

• Doppler shifted RT instability ( $\mathbf{B} = \hat{\mathbf{B}} = 0$ ,  $\mathbf{v} = \hat{\mathbf{v}}$ ,  $\mathbf{k}_0 \parallel \mathbf{v}$ ):

$$\omega = k_0 v \pm i \sqrt{\frac{k_0(\rho - \hat{\rho})g}{\rho + \hat{\rho}}}.$$
(41)

 $\Rightarrow$  Degeneracy of Doppler mode  $\omega = k_0 v$  lifted by  $\rho \neq \hat{\rho}$ .

• Hence, generic *transitions to instability* for (a) static, and (b) stationary plasmas:



Exp. growth: through origin

Overstability: through real axis

#### Kelvin–Helmholtz instability: generalizations

 Of course, the assumption of two homogeneous plasma layers with a velocity difference at the interface (made to make the analysis tractable for a relevant instability) evades the basic problems of diffuse plasma flows: continuous spectra, cluster points, and *eigenvalues on unknown paths in the complex* ω *plane*.

 $\Rightarrow$  Further progress only by *linear computational methods:* finite differences and finite elements, spectral methods, linear system solvers, etc.

• Instabilities always grow towards amplitudes that necessitate consideration of the **nonlinear evolution**: *coupling of linear modes, nonlinear saturation, and turbulence* appear: see simulation of Rayleigh–Taylor instability with Versatile Advection Code, where secondary Kelvin–Helmholtz instabilities develop (sheet 6-42).

 $\Rightarrow$  Further progress mainly by *nonlinear computational methods:* implicit and semiimplicit time stepping, finite volume methods, shock-capturing methods, etc. Waves and instabilities in stationary plasmas: Cylindrical plasmas (1)

Recap.: MHD wave equation in cylinder (static) [Vol. 1: Chap. 9]

- Fourier harmonics  $\hat{\boldsymbol{\xi}}(r;m,k) \exp [i(m\theta + kz)]$ , keep differential operators d/dr.
- *Field line projection* in normal, perpendicular, and parallel directions:

MHD spectral equation  $\mathbf{F}(\boldsymbol{\xi}) = -\rho\omega^2 \boldsymbol{\xi}$  (+ algebra!)  $\Rightarrow$  Vector eigenvalue problem:

$$\begin{pmatrix} \frac{d}{dr} \frac{\gamma p + B^2}{r} \frac{d}{dr} r - F^2 - r \left(\frac{B_{\theta}^2}{r^2}\right)' \frac{d}{dr} \frac{G}{B} (\gamma p + B^2) - 2 \frac{k B_{\theta} B}{r} \frac{d}{dr} \frac{F}{B} \gamma p \\ - \frac{G}{B} \frac{\gamma p + B^2}{r} \frac{d}{dr} r - 2 \frac{k B_{\theta} B}{r} - \frac{G^2}{B^2} (\gamma p + B^2) - F^2 - \frac{FG}{B^2} \gamma p \\ - \frac{F}{B} \frac{\gamma p}{r} \frac{d}{dr} r - \frac{FG}{B^2} \gamma p - \frac{FG}{B^2} \gamma p \end{pmatrix} \begin{pmatrix} \xi \\ \eta \\ \zeta \end{pmatrix} = -\rho \omega^2 \begin{pmatrix} \xi \\ \eta \\ \zeta \end{pmatrix}.$$

$$(45)$$

• Eliminate perpendicular and parallel components  $\eta$  and  $\zeta$ :

$$\eta = \frac{\rho(\gamma p + B^2)G(\omega^2 - \omega_S^2) r\chi' + 2kB_{\theta}(B^2\rho\omega^2 - \gamma pF^2)\chi}{r^2 BD},$$

$$\zeta = \frac{\rho\gamma pF[(\omega^2 - \omega_A^2) r\chi' + 2kB_{\theta}G\chi]}{r^2 BD},$$
(46)

• Substitute in 1st component  $\Rightarrow$  generalized Hain–Lüst equation:

$$\frac{d}{dr} \left[ \frac{N}{rD} \frac{d\chi}{dr} \right] + \frac{1}{r} \left[ \rho \omega^2 - F^2 - r \left( \frac{B_{\theta}^2}{r^2} \right)' - \frac{4k^2 B_{\theta}^2}{r^2 D} (B^2 \rho \omega^2 - \gamma p F^2) + r \left\{ \frac{2k B_{\theta} G}{r^2 D} ((\gamma p + B^2) \rho \omega^2 - \gamma p F^2) \right\}' \right] \chi = 0, \quad (47)$$

with singular factors

$$N = N(r; \omega^2) \equiv \rho^2 (\gamma p + B^2) (\omega^2 - \omega_A^2) (\omega^2 - \omega_S^2),$$
  

$$D = D(r; \omega^2) \equiv \rho^2 \omega^4 - (m^2/r^2 + k^2) (\gamma p + B^2) (\omega^2 - \omega_S^2).$$
(48)

• BCs:

$$\chi(0) = \chi(a) = 0$$
 (including  $m = 1$  at  $r = 0$ ). (49)

#### MHD wave equation in cylinder with flow

Generalizing the MHD wave equation to equilibria with background flow, exploiting the MHD spectral equation G(ξ) + 2iρωv · ∇ξ + ρω<sup>2</sup>ξ = 0 (+ a lot of algebra!)
 ⇒ Quadratic vector eigenvalue problem:

$$\begin{bmatrix} \mathbf{F}_{0} + \begin{pmatrix} -r\rho \left(\frac{\Phi_{\mathrm{gr}}'}{r}\right)' & -\Lambda \frac{G}{B} & -\Lambda \frac{F}{B} \\ -\Lambda \frac{G}{B} & 0 & 0 \\ -\Lambda \frac{F}{B} & 0 & 0 \end{pmatrix} - 2\rho \frac{v_{\theta}}{r} \widetilde{\omega} \begin{pmatrix} 0 & \frac{B_{z}}{B} & \frac{B_{\theta}}{B} \\ \frac{B_{\theta}}{B_{z}} & 0 & 0 \\ \frac{B_{\theta}}{B_{\theta}} & 0 & 0 \end{pmatrix} + \rho \widetilde{\omega}^{2} \mathbf{I} \end{bmatrix} \begin{pmatrix} \xi \\ \eta \\ \zeta \end{pmatrix} = 0, \quad (50)$$

where  $\mathbf{F}_0$  is the matrix on the LHS of the static wave equation (45), the function  $\Lambda(r) \equiv \rho(v_{\theta}^2/r - \Phi_{\rm gr}')$  represents the deviation from static equilibrium due to rotation and gravity (or the deviation of HD equilibria from Keplerian flow), the Doppler shifted frequency  $\widetilde{\omega}(r) \equiv \omega - \Omega_0(r)$ , where  $\Omega_0 \equiv m v_{\theta}/r + k v_z$ , and I is the unit matrix.

• Elimination of  $\eta$  and  $\zeta$  and substitution in the first component, yields again a 2nd order ODE like the Hain–Lüst equation: see Eq. (51) below.

### **Observations**

Young Stellar Object ( $M_* \sim 1 M_{\odot}$ )



disk and jets

#### Active Galactic Nucleus (~ $10^8 M_{\odot}$ )



disk (optical) and jets (radio)

### Magneto-rotational instability

- Example of **cylindrical flow.** Original references:
  - Velikhov, Soviet Phys.-JETP Lett. 36, 995 (1959);
  - Chandrasekhar, Proc. Nat. Acad. Sci. USA 46, 253 (1960).
- Applied to *accretion disks* by Balbus and Hawley, Astrophys. J. **376**, 214 (1991). Problem: how can accretion on Young Stellar Object (mass  $M_* \sim M_{\odot}$ ) or Active Galactic nucleus (mass  $M_* \sim 10^9 M_{\odot}$ ) occur at all on a reasonable time scale?
  - Without dissipation impossible, because disk would conserve angular momentum; some form of viscosity needed to transfer angular momentum to larger distances.
  - However, ordinary molecular viscosity much too small to produce sizeable transfer, and for turbulent increase (small-scale instabilities) no HD candidates were found.
  - It is generally assumed that the resolution of this problem involves MHD instability: the magneto-rotational instability (MRI).
- Simplify the axi-symmetric (2D) representation of the disk (see sheet 4-9) even further by *neglecting vertical variations* so that a cylindrical (1D) slice is obtained.
   [One should object: but that is no disk at all anymore! Yet, this is how plasma-astrophysicists grapple with the problem of anomalous (turbulent) transport.]

#### MRI: cylindrical representation

• Generalization of Hain–Lüst equation, Book, Eq. (9.31), to cylindrical flow with normal modes  $\boldsymbol{\xi} \sim \exp\left[i(m\theta + kz - \omega t)\right],$ 

again yields second order ODE for radial component of the plasma displacement:

$$\frac{d}{dr}\left[\frac{N}{rD}\frac{d\chi}{dr}\right] + \left[U + \frac{V}{D} + \left(\frac{W}{D}\right)'\right]\chi = 0, \qquad \chi \equiv r\xi.$$
(51)

[Bondeson, Iacono and Bhattacharjee, Phys. Fluids **30**, 2167 (1987);

extended with gravity: Keppens, Casse, Goedbloed, Astrophys. J. 579, L121 (2002)]

• Assumption of *small magnetic field*,

$$\beta \equiv 2p/B^2 \gg 1\,,\tag{52}$$

justifies use of this spectral equation in the incompressible limit:

$$\frac{d}{dr} \left[ \frac{\rho \widetilde{\omega}^2 - F^2}{m^2 + k^2 r^2} r \frac{d\chi}{dr} \right] - \frac{1}{r} \left[ \rho \widetilde{\omega}^2 - F^2 + r \left( \frac{B_{\theta}^2 - \rho v_{\theta}^2}{r^2} \right)' + \rho' \Phi_{\rm gr}' - \frac{4k^2 (B_{\theta}F + \rho v_{\theta} \widetilde{\omega})^2}{(m^2 + k^2 r^2)(\rho \widetilde{\omega}^2 - F^2)} - r \left( \frac{2m (B_{\theta}F + \rho v_{\theta} \widetilde{\omega})}{r(m^2 + k^2 r^2)} \right)' \right] \chi = 0.$$
(53)



• Gravitational potential of compact object is approximated for cylindrical slice,

$$\Phi_{\rm gr} = -GM_*/\sqrt{r^2 + z^2} \approx -GM_*/r \,, \tag{54}$$

with short wavelengths fitting the disk in the vertical direction:

$$k\,\Delta z \gg 1\,.\tag{55}$$

• Incompressibility is consistent with *constant density* so that the only gravitational term,  $\rho' \Phi'_{\rm gr}/r$ , disappears from the spectral equation. However,  $\Phi_{\rm gr}$  does not disappear from the equilibrium equation that  $\rho$ , p,  $B_{\theta}$ ,  $B_z$ , and  $v_{\theta}$  have to satisfy,

$$(p + \frac{1}{2}B^2)' + \frac{1}{r}B_{\theta}^2 = \frac{1}{r}\rho v_{\theta}^2 - \rho \Phi_{\rm gr}',$$

so that stability will still be influenced by gravity.

### MRI: further approximations

• Assume purely vertical and constant magnetic field and purely azimuthal velocity,

$$B_{\theta} = 0, \quad v_z = 0 \quad \Rightarrow \quad \omega_A = k B_z / \sqrt{\rho} = \text{const}, \quad \Omega_0 = m v_{\theta} / r,$$
 (56)

and restrict analysis to vertical wave numbers k only,

$$m = 0 \quad \Rightarrow \quad \Omega_0 = 0 \quad \Rightarrow \quad \widetilde{\omega} = \omega \,.$$
 (57)

In the spectral equation, only  $\omega^2$  appears:  $\omega = 0$  remains the marginal point!

$$\left(\omega^2 - \omega_A^2\right) \frac{d}{dr} \left(\frac{1}{r} \frac{d\chi}{dr}\right) - \frac{k^2}{r} \left[\omega^2 - \omega_A^2 - r \left(\frac{v_\theta^2}{r^2}\right)' - \frac{4\omega^2 v_\theta^2 / r^2}{\omega^2 - \omega_A^2}\right] \chi = 0.$$
(58)

• Introduce angular frequency  $\Omega \equiv v_{\theta}/r$  and epicyclic frequency  $\kappa$ ,

$$\kappa^2 \equiv \frac{1}{r^3} (r^4 \Omega^2)' = 2r \Omega \Omega' + 4\Omega^2 \tag{59}$$

(Specific angular momentum  $L \equiv \rho r v_{\theta} \equiv \rho r^2 \Omega$ ; hence  $\kappa^2 = 0 \Rightarrow L' = 0$ .) The spectral equation then becomes:

$$\left(\omega^2 - \omega_A^2\right) \frac{d}{dr} \left(\frac{1}{r} \frac{d\chi}{dr}\right) - \frac{k^2}{r} \left[\omega^2 - \omega_A^2 - \kappa^2(r) - \frac{4\omega_A^2 \Omega^2(r)}{\omega^2 - \omega_A^2}\right] \chi = 0.$$
 (60)

## MRI: criteria

• Recall construction of quadratic form (sheet 7-24e):

$$(P\chi')' - Q\chi = 0 \qquad \Rightarrow \quad \int (P\chi'^2 + Q\chi^2) \, r \, dr = 0 \,. \tag{61}$$

 $\Rightarrow$  For eigenfunctions (oscillatory  $\chi$ ), we should have Q/P < 0 for some r.

• From Eq. (60), this gives the following *criteria for instability* ( $\omega^2 < 0$ ):

(a) MHD ( $\omega_A^2 \neq 0$ ):  $\omega_A^2 + \kappa^2 - 4\Omega^2 < 0$ (b) HD ( $\omega_A^2 \equiv 0$ ):  $\kappa^2 < 0$  (for some range of r). (62)

• For *Keplerian rotation* (neglecting p and B on equilibrium motion):

$$\frac{1}{r}\rho v_{\theta}^2 = \rho \Phi_{\rm gr}' = \rho \frac{GM_*}{r^2} \quad \Rightarrow \quad \Omega^2 = \frac{GM_*}{r^3} \quad \Rightarrow \quad \kappa^2 = \frac{GM_*}{r^3} > 0.$$
 (63)

 $\Rightarrow$  In HD limit, opposite of (62)(b) holds, *Rayleigh's circulation criterion is satisfied:* the fluid is stable to axi-symmetric modes (m = 0) if  $\kappa^2 \ge 0$  everywhere.

This explains the interest in MHD instabilities as candidates for turbulent increase of the dissipation processes in accretion disks.

## MRI: MHD versus HD

• MHD instability criterion in the limit  $\omega_A^2 \rightarrow 0$  (magnetic field sufficiently small):

$$\kappa^2 - 4\Omega^2 \equiv 2r\Omega\Omega' < 0.$$
(64)

This is **satisfied for Keplerian disks:** MRI works for astrophysically relevant cases! Stabilizing field contribution ( $\omega_A^2 > 0$ ) should be small enough to maintain this effect.

- Discrepancy of HD and MHD stability results is due to *interchange of limits:* HD disk: ω<sub>A</sub><sup>2</sup> = 0, ω<sup>2</sup> → 0, MHD disk: ω<sup>2</sup> = 0, ω<sub>A</sub><sup>2</sup> → 0. This is resolved when the *growth rates* of the instabilities are considered.
- Instead of numerically solving ODE (60), just consider radially localized modes,  $\chi \sim \exp(iqr), \ q \Delta r \gg 1$ , producing a *local dispersion equation:*

$$(k^{2} + q^{2})(\omega^{2} - \omega_{A}^{2})^{2} - k^{2}\kappa^{2}(\omega^{2} - \omega_{A}^{2}) - 4k^{2}\omega_{A}^{2}\Omega^{2} = 0.$$
 (65)

Solutions for  $q^2 \ll k^2$ :

$$\omega^{2} = \omega_{A}^{2} + \frac{1}{2}\kappa^{2} \pm \frac{1}{2}\sqrt{\kappa^{4} + 16\omega_{A}^{2}\Omega^{2}} \approx \begin{cases} \kappa^{2} + \omega_{A}^{2}(1 + 4\Omega^{2}/\kappa^{2}) \\ \omega_{A}^{2}(1 - 4\Omega^{2}/\kappa^{2}) \end{cases}, \quad (66)$$

 $\text{Limit } \omega_A^2 \to 0 \text{ : (1) Rayleigh mode (HD), } \omega_+^2 \to \kappa^2 > 0 \text{ , (2) MRI (MHD), } \omega_-^2 \to 0 \text{ .}$ 

### MRI: Numerical results

[Keppens, Casse, Goedbloed, ApJ 579, L121 (2002)]

- Full spectrum with toroidal field (m = 0)
  - $\Rightarrow$  Discrete MRIs form cluster spectrum towards slow continuum:



### MRI: Numerical results

[Keppens, Casse, Goedbloed, ApJ 579, L121 (2002)]

- Full spectrum with toroidal field (m = 10)
  - $\Rightarrow$  Many more unstable sequences in the complex  $\omega$ -plane:

